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# MULTI-OBJECTIVE OPTIMIZATION FOR SPEED AND STABILITY OF A SONY AIBO GAIT



Multi-Objective Optimization  
for Speed and Stability of a  
Sony AIBO Gait

Air Force Institute of Technology (U.S.)  
Graduate School of Engineering and  
Management

Biblioscholar, United States, 2012. Paperback. Book Condition: New. 246 x 189 mm. Language: English . Brand New Book \*\*\*\*\* Print on Demand \*\*\*\*\*.As part of the RoboCup 4-legged league, many researchers have worked on increasing the walking/gait speed of Sony AIBO robots. Recently, the effort shifted from developing a quick gait, to developing a gait that also provides a stable sensing platform. However, to date, optimization of both velocity and camera stability has only occurred using a single fitness function that...

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- Authored by Christopher A Patterson
- Released at 2012



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## Reviews

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